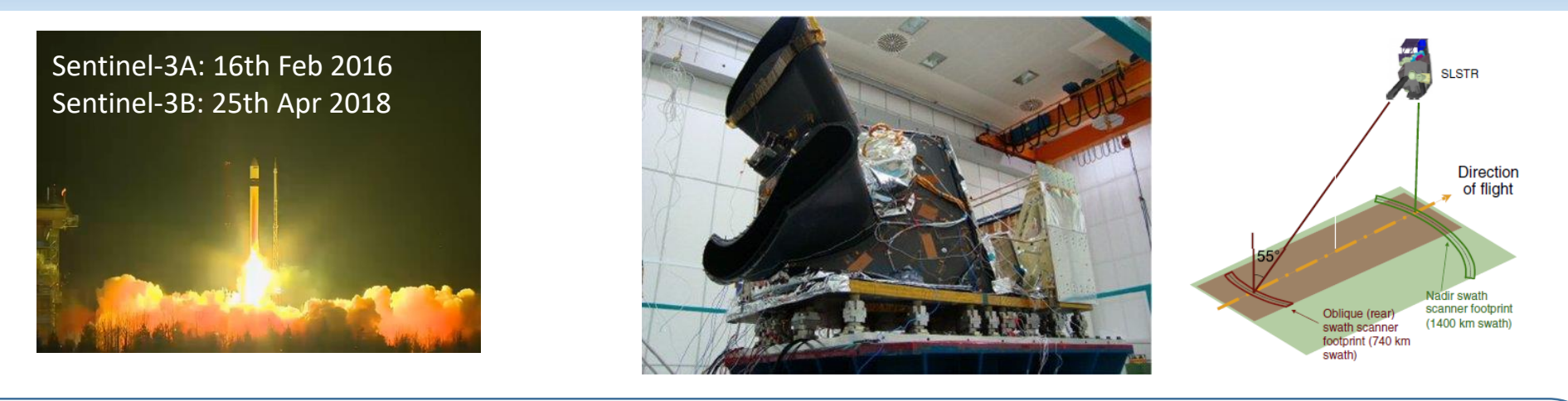


Requirement on SLSTR SST product performance: absolute accuracy should be better than 0.3 K and its temporal stability better than 0.1 K/decade. Comparison against in situ reference measurements using SST multi-mission matchup database (MMDB) is performed to confirm this requirement. We are providing here status and information about generated SLSTR SST MDB used to perform this activity.



**Satellite SST**

SLSTR-A/B SST + SLSTR L1 (EUMETSAT)

AVHRR-B SST (OSI-SAF)

IASI-B SST (OSI-SAF)

VIIRS SST (PODAAC OSPO)

**In situ SST**

Copernicus in situ service  
Drifting buoys, Argo, moored

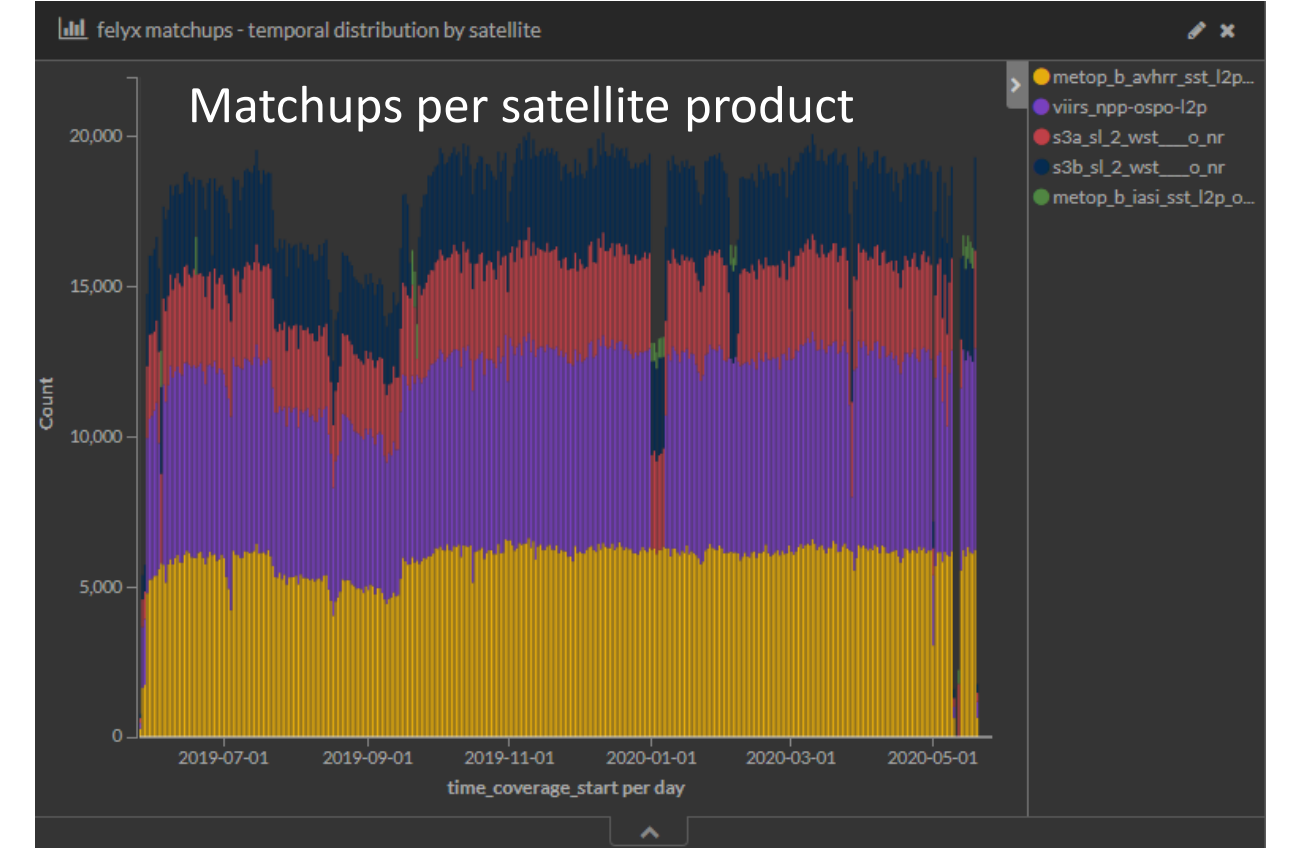
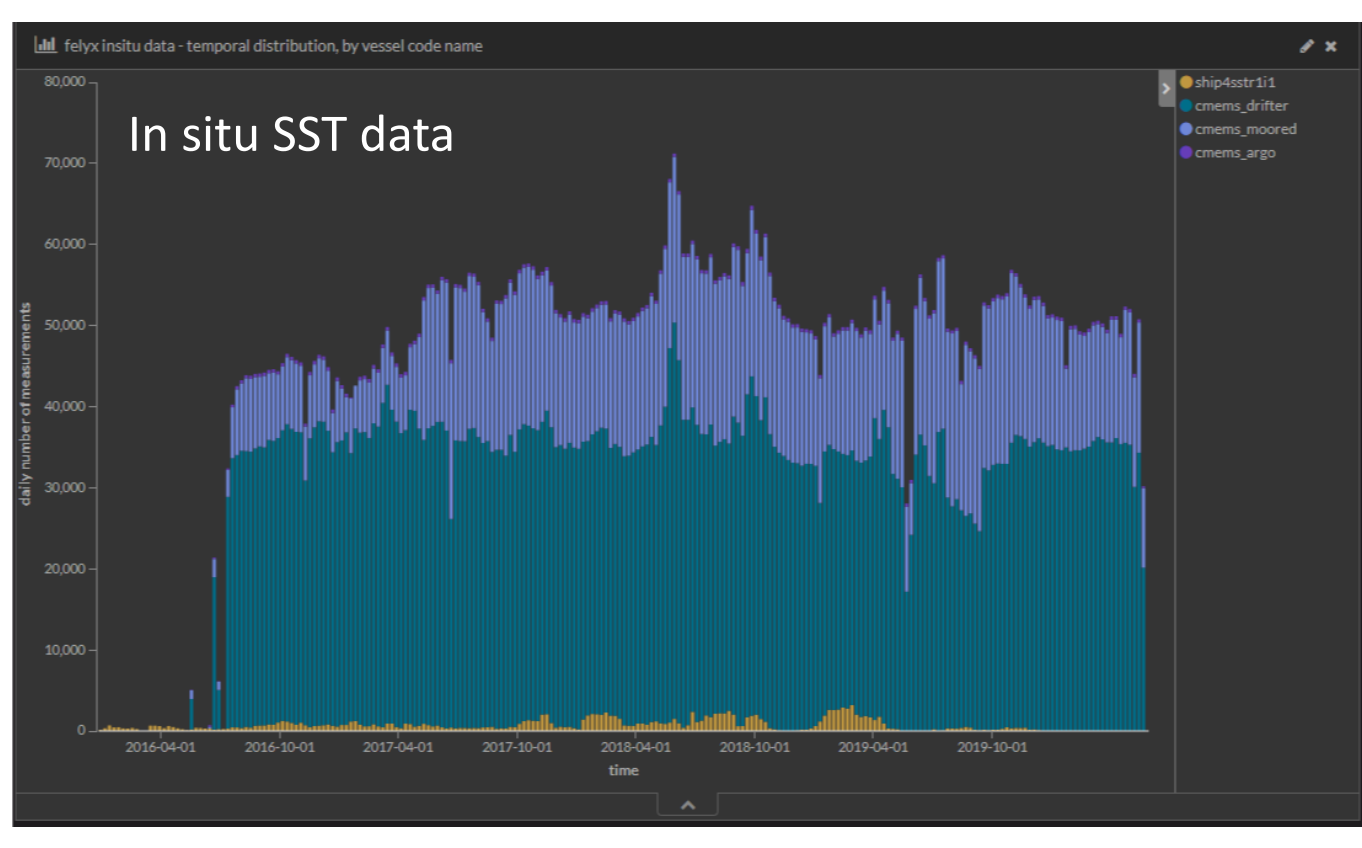
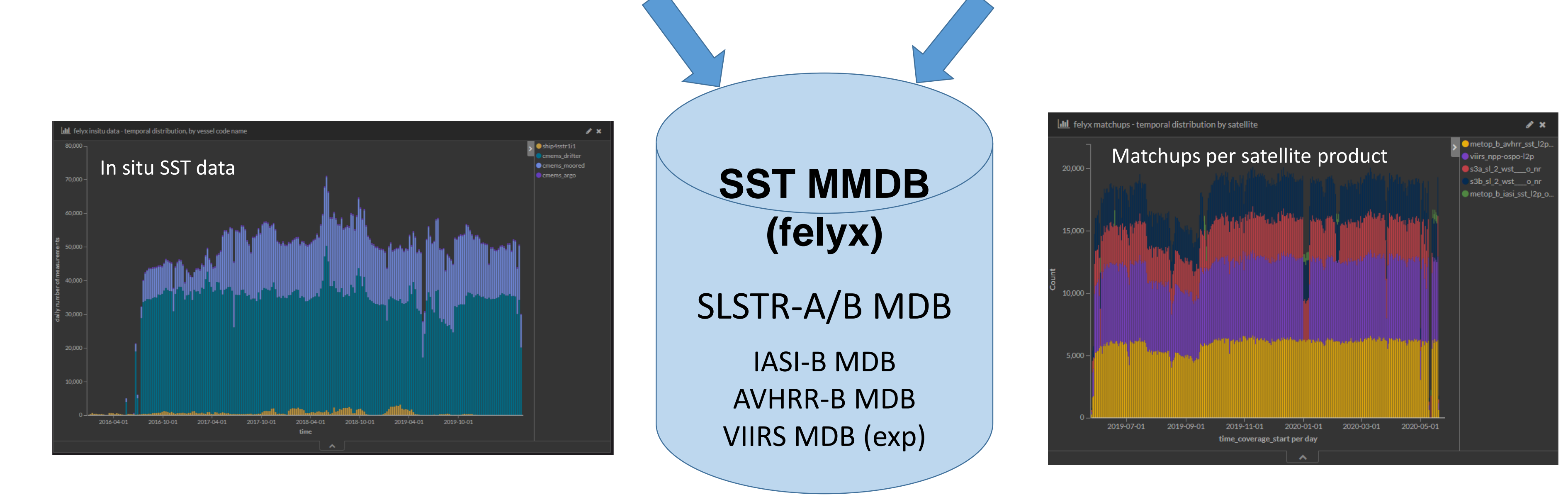
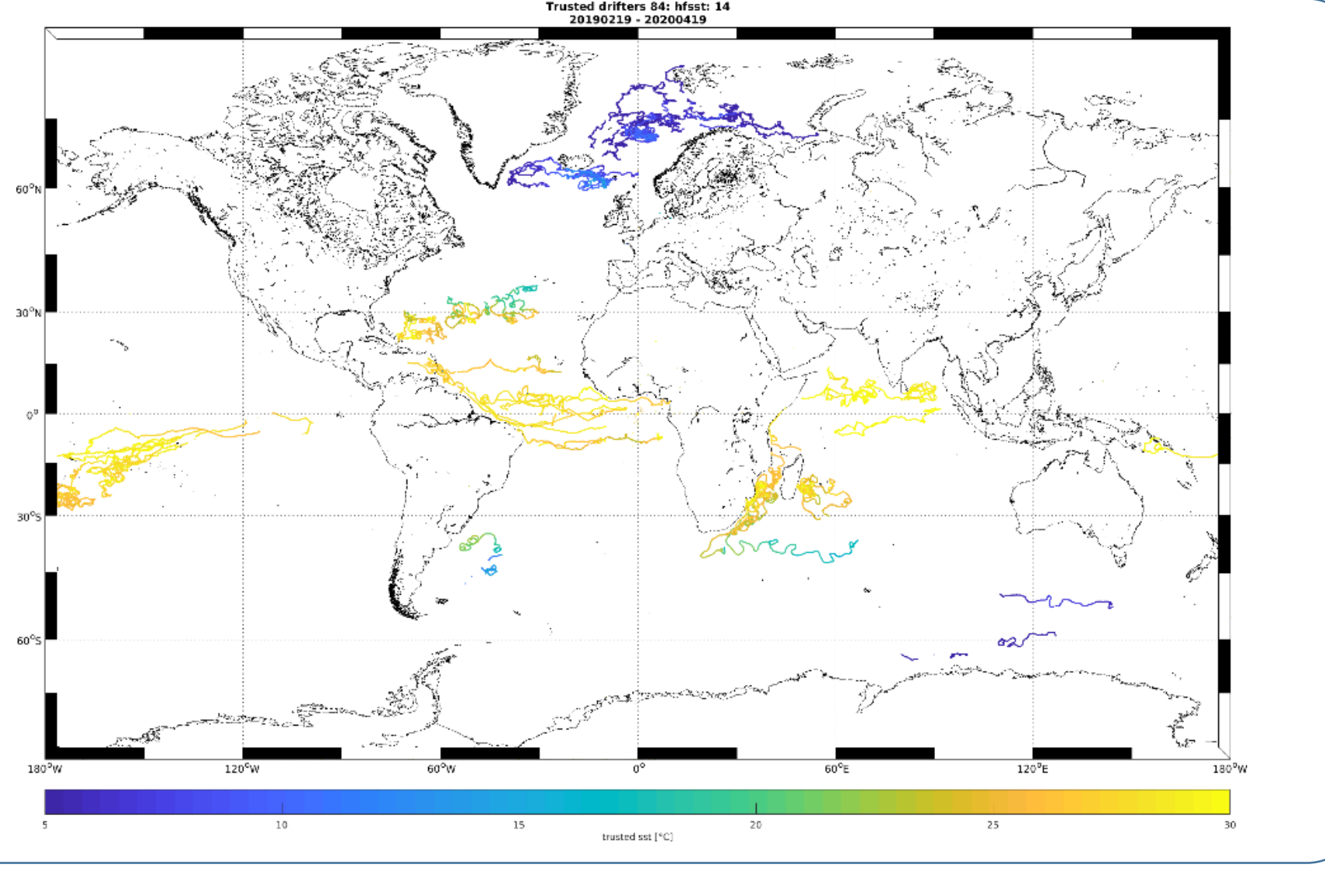
Radiometers FRM  
Ship4sst (ISAR, M-AERI, SISTeR)

**TRUSTED**

Saildrone (to be included)

**TRUSTED**

- Full access to all trusted variables:
  - Digital/analog SST
  - High-frequency measurements
  - Additional variables from raw data
- Check HRSST talk #011 from Gary
- Soon available to S3VT users as additional AUX file:  
e.g. s3a\_sl\_2\_wst\_\_\_o\_nr\_cmems\_drifter\_aux\_trusted\_20200330000000\_20200330060000.nc



**STATUS**

- Migrated (07/2019) to internal EUM infrastructure
- Running (daily – with 1 week delay)
- Revised radiometer dataset (ship4sstr1i1)
  - Added new variables
- Processed
  - S3A Repro MDB: 2016/08-2018/04
  - S3A NRT MDB: 2018/04-2018/12
  - S3A/B NRT MDB: 2019 - today
- Consolidated NRT MDB format
- Fixed issues
  - Matchup generation for orbits (NTC)

**Next**

**Short term (>>1 month)**

- Radiometers (ship4sstr1i1): reprocess 01/2019 – today
  - Currently only ISAR available from 04/2019-
  - Include saildrone for the same period
- MDB format specification (TEN) + product notice

• MDB in S3A early commissioning (05-07/2016)

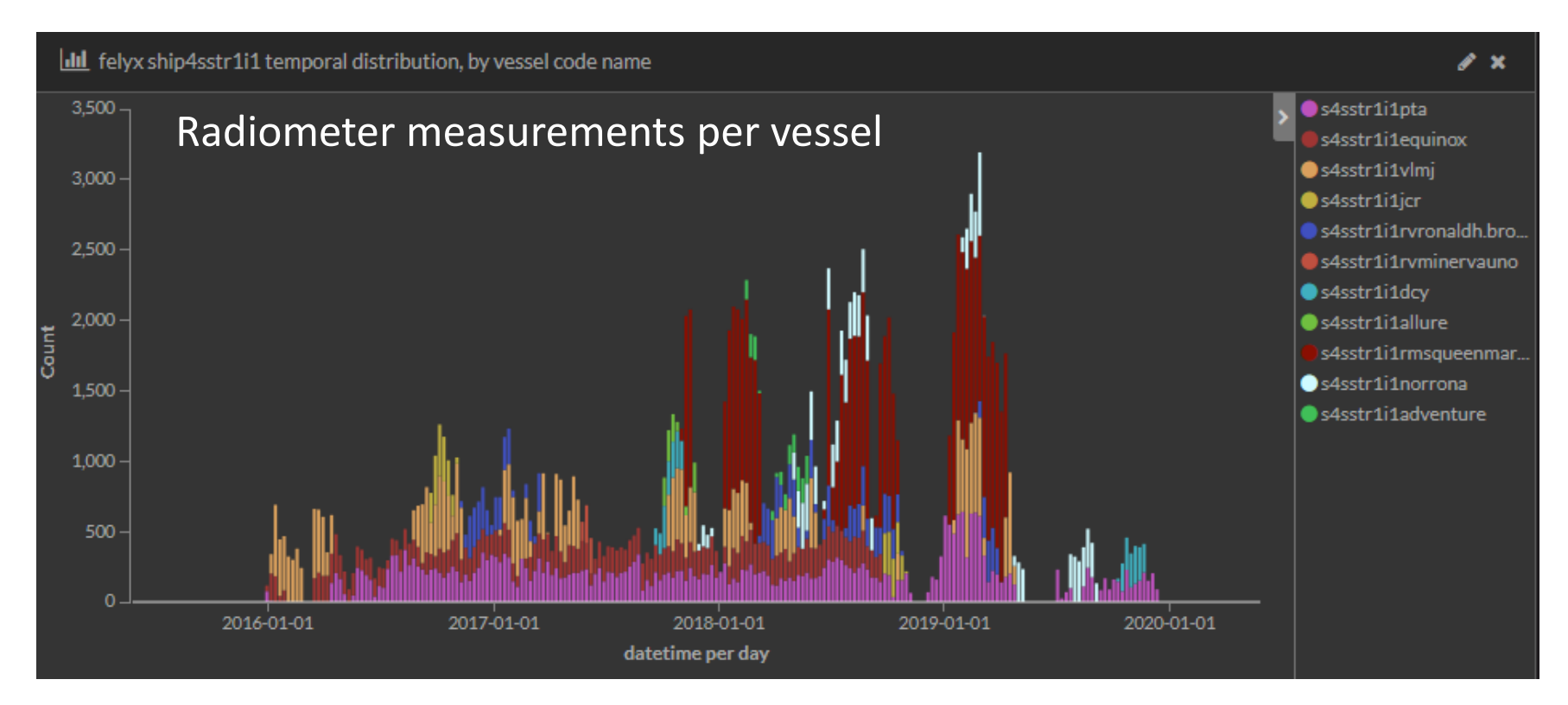
• S3A/S3B tandem phase (for S3B) – all in situ types

• RTM (RTTOV) and FKC (SST adjustments)

• On line analysis

**Long term (> 1 y)**

Reliability, robustness, performance, installation, monitoring, analysis, ...



**SLSTR MDB format**

- split in core MDB + 4 aux MDBs (netcdf files):
- WST + WCT, MET, RBT-i, RBT-a
- Per in situ type
  - Drifters (in NRT) every 6 h
  - Argo, moored, radiometers: 1 per day
- Variables:
  - <parent><variable> (e.g. "s3a\_sl\_2\_wst\_\_\_o\_nr\_lat")
  - All L2p variables and selected L1
- Extracts
  - 21x21 or 401x401 (ship4sstr1i1) pixels in i-grid (1 km)
  - a-grid (500 m) is twice the size
  - MET data: only TCWV is full extract, others are center pixel only
- In situ history around matchup

**SLSTR MDB naming convention**

**Path**

/mdb/<mdb\_name>/<YYYY>/<DDD>/<mdb\_name>:

operational:  
mdb\_eum\_slstr-sst\_nrt\_ope  
mdb\_eum\_slstr-sst\_nrt\_ope\_aux

reprocessed:  
s3a\_slstr\_eum\_rep\_l2wst\_mdb  
s3a\_slstr\_eum\_rep\_l2wst\_mdb\_aux

**Filename**

CORE:  
<prod\_name>\_<insitu\_type>\_<start\_date>\_<stop\_date>.nc

AUX:  
<prod\_name>\_<insitu\_type>\_aux\_<aux\_name>\_<start\_date>\_<stop\_date>.nc

<prod\_name>: s3a\_sl\_2\_wst\_\_\_o\_nr, s3b\_sl\_2\_wst\_\_\_o\_nr

<insitu\_type>: cmems\_drifter, cmems\_argo, cmems\_moored, ship4sstr1i1

<aux\_name>: met (meteorological parameters)  
rbt-a (500 m VIS/NIR channels)  
rbt-i (1 km IR channels)  
wct (SST algorithms: N2, N3, D2, D3)

Examples:  
s3a\_sl\_2\_wst\_\_\_o\_nr\_cmems\_argo\_20200519000000\_20200520000000.nc  
<prod\_name>\_cmems\_argo\_aux\_met\_20200519000000\_20200520000000.nc

**SLSTR MDB Access**

Access available to all Sentinel-3 Validation Team (S3VT) members.

To become S3VT member please submit proposal ([s3vt.org](https://s3vt.org)) and request access to SLSTR MDB. For more information send email to Anne ([Anne.Ocarroll@eumetsat.int](mailto:Anne.Ocarroll@eumetsat.int)).

**Further information** <https://slstr.eumetsat.int>

[Sentinel-3 SLSTR Marine User Handbook](#)