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# A consistent day/night SST regression algorithm based on 3-channel AVHRR

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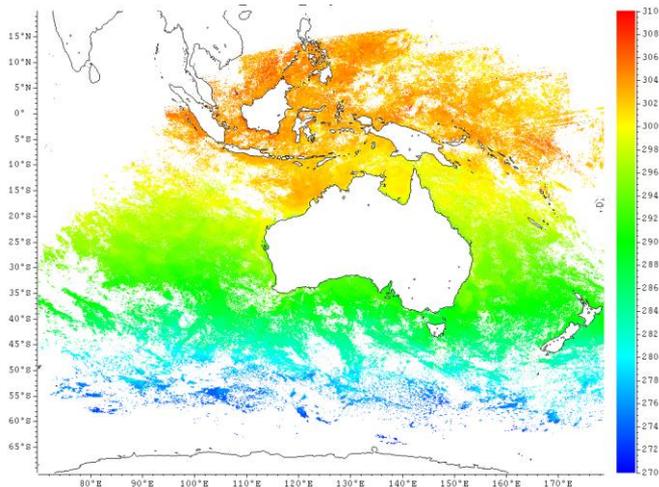
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EARWiG Breakout Session, 14<sup>th</sup> GHRSSST Science Team Meeting, Woods Hole, 17-21 June 2013



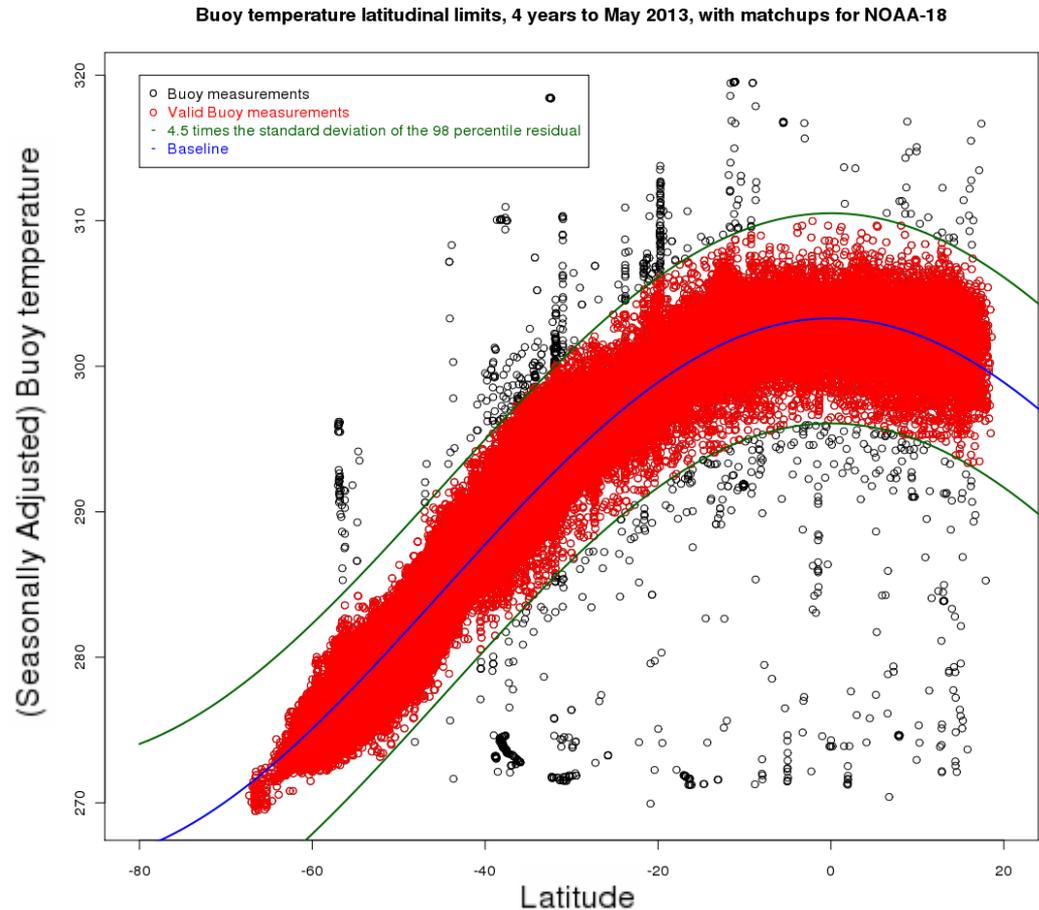
# Scale Tuning (Climatology)



6 day composite (NOAA 18/19), 1 June 2013

$$T = T_0 + \kappa_l \sin^2(\text{lat}) + \kappa_s \sin(2\pi\tau + \phi)$$

$\tau$  time of year  
 $\phi$  seasonal phase shift



Buoy temperature latitudinal limits, 4 years to May 2013, with matchups for NOAA-18

4 Year Buoy measurements in view of NOAA-18, 9 May 2013

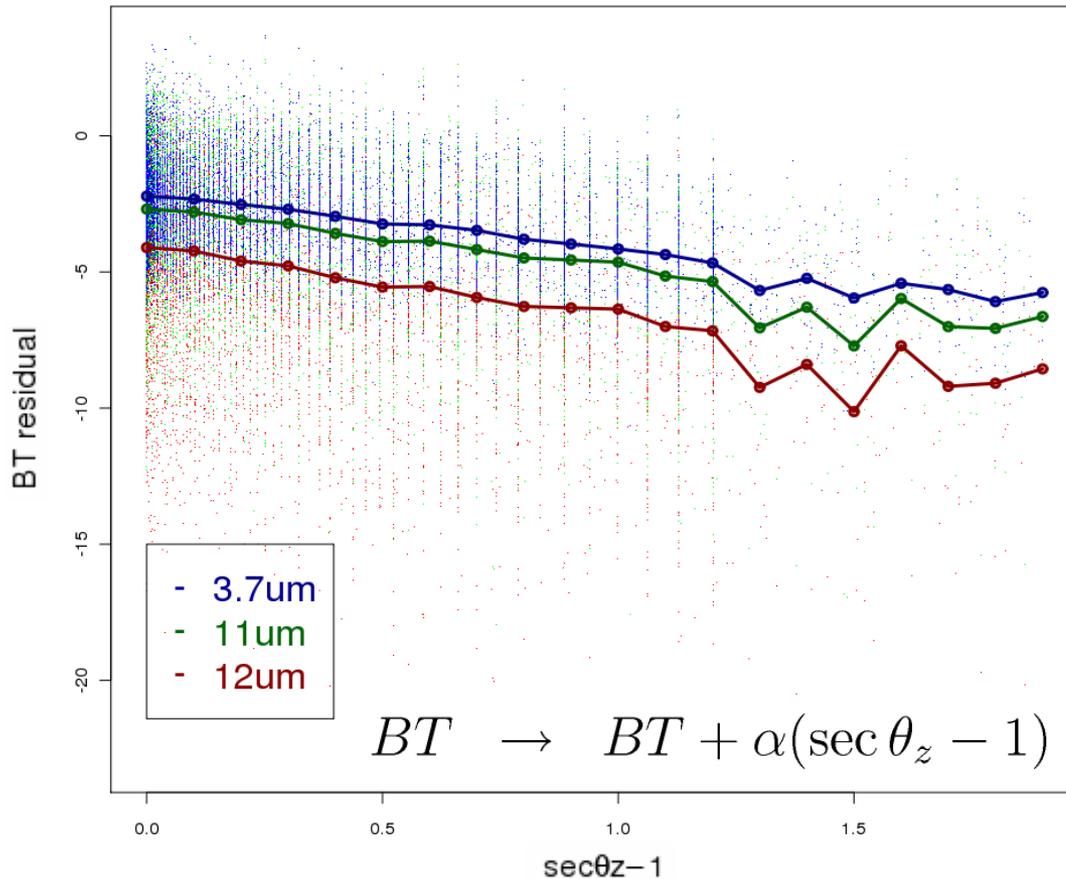


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# Compensating for $\theta_z$

Brightness temperature residual from scale vs  $\sec\theta_z-1$



View angle dependence:

- is a geometrical artefact
- is linear in  $\sec \theta_z$  to first order and does not scale with the brightness temperature
- applies to each brightness temperature, since it is geometrical in nature
- Use the deviation from the Scale Tuning (Climatology)
- “does not / should not” require matching *in situ* measurements to correct for

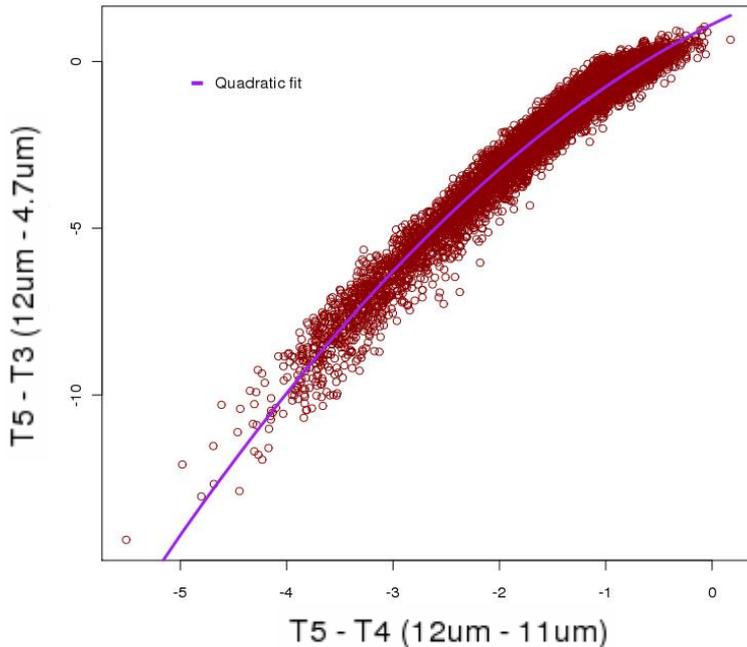


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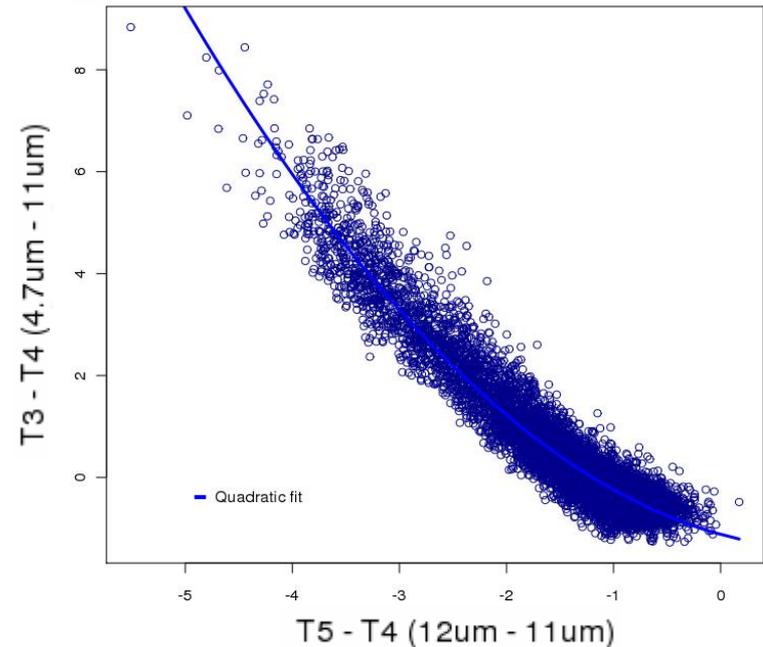
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# Connecting the Three Channels

Night  $\theta z$  adjusted brightness temperature differences



Night  $\theta z$  adjusted brightness temperature differences



- Differences between brightness temperatures characterise and correct for atmospheric conditions.
- There is a single largest “primary factor” (atmospheric water). This will result in a pair-wise non-linear correlation between the temperature differences.



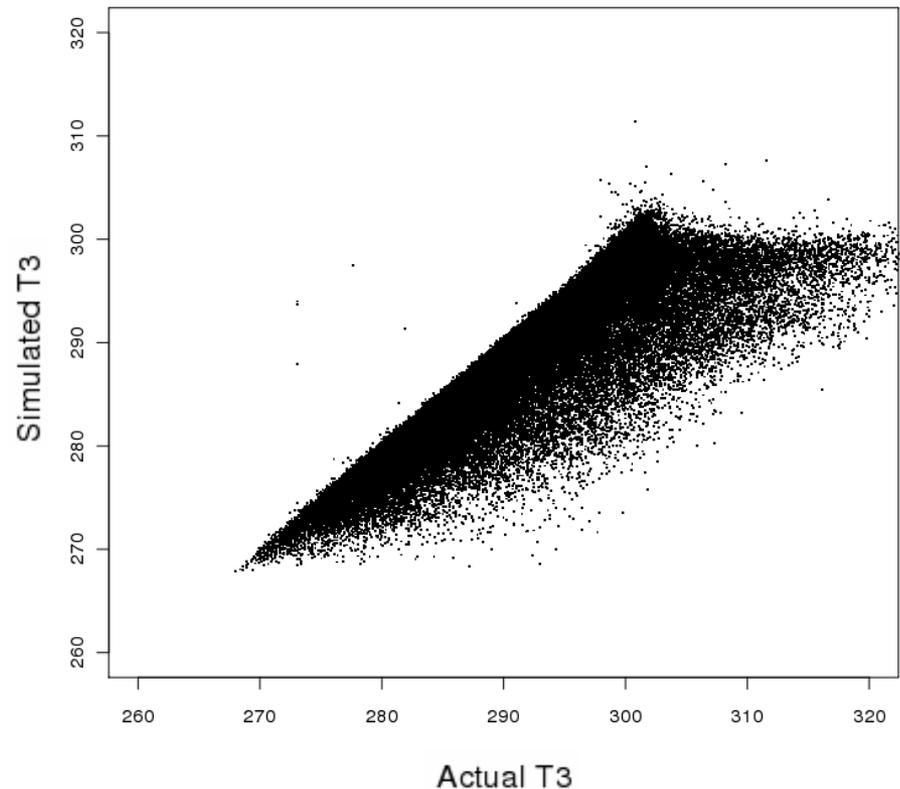
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# Forming a 3<sup>rd</sup> Day Channel

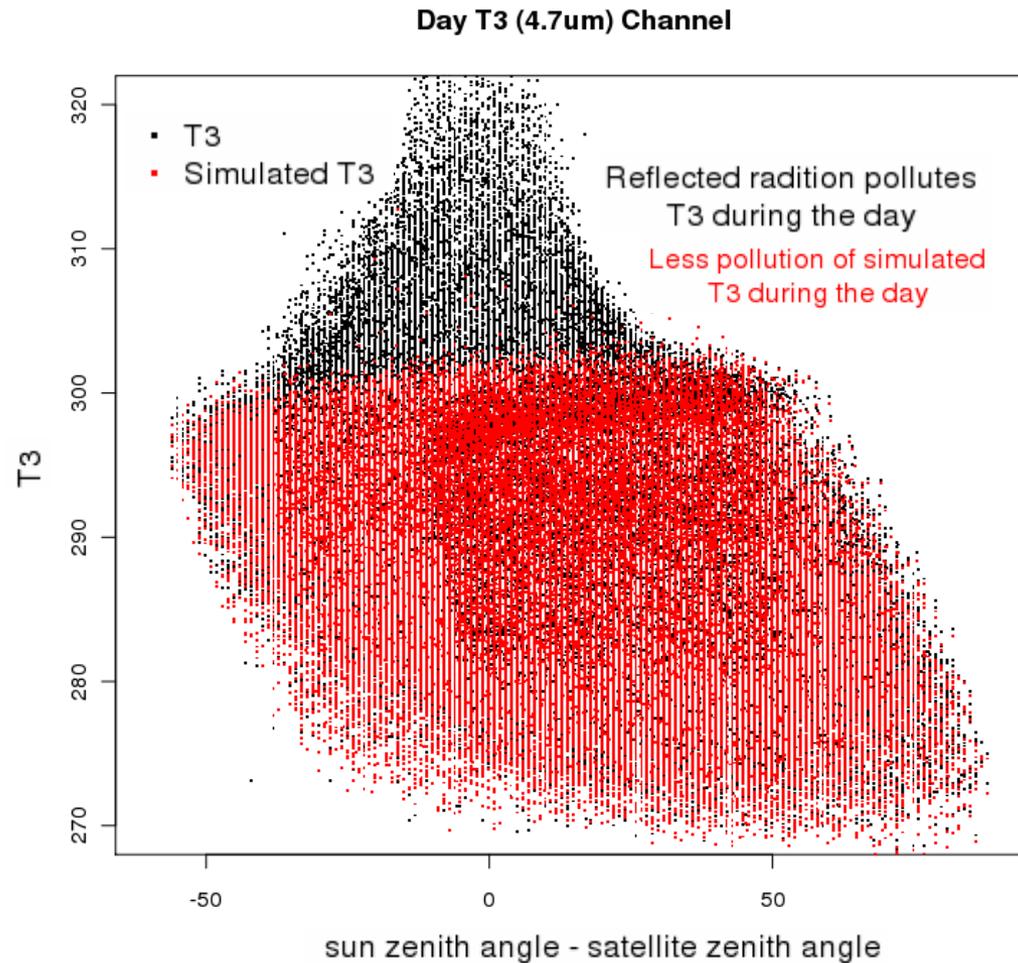
- Assume that the same “primary factor” is dominant during the day.
- $T_3 - T_4$  and  $T_5 - T_3$  can be estimated from  $T_5 - T_4$
- These in turn can provide a simulated  $T_3$  during day time.
- At night, continue to use the measured  $T_3$

Day Simulated T3 vs Actual T3





# Correcting / Detecting Reflected Contamination





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# Tuning with a Tri-linear Rule

- We Scale Tuned without satellites
- We Compensated for  $\theta_z$  without *in situ* measurements (almost)
- We Guessed  $T_3$  during the Day without *in situ*
- We have no analysis SST in our equation
- Now we can Tune for SST

$$T = aT_4 + b(T_3 - T_5) + c(T_5 - T_4)$$

**Day and Night can have the same parameters !**



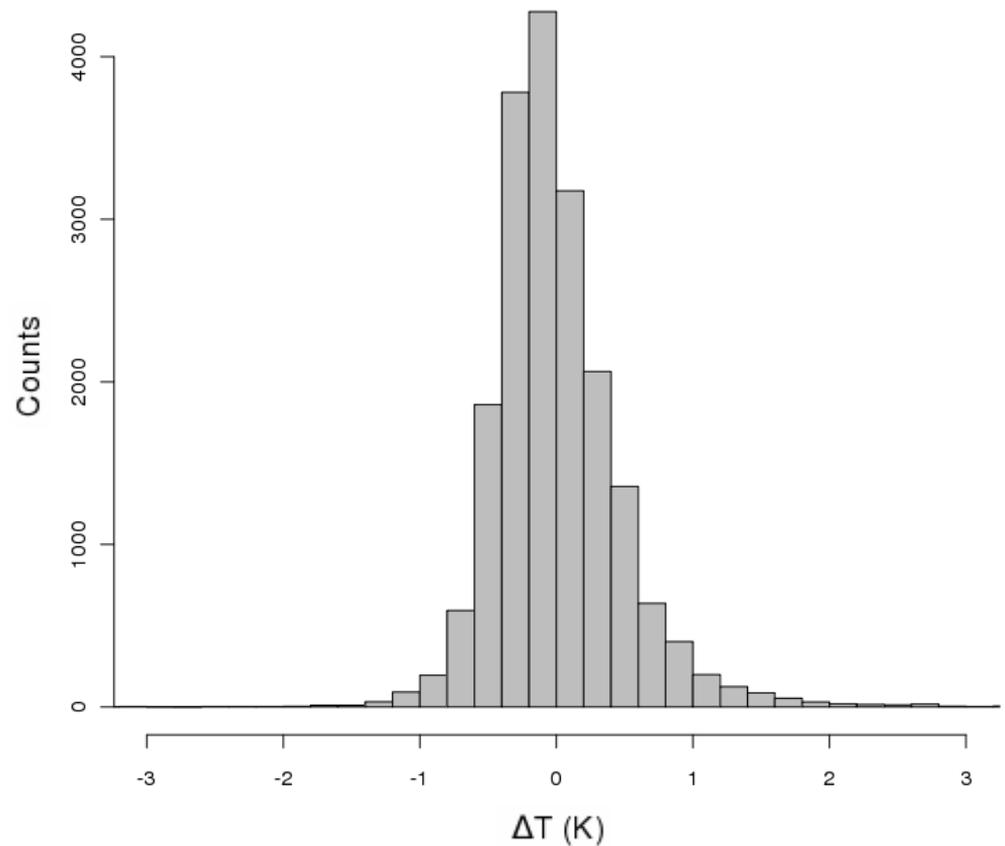
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# Performance against *in situ*

$\mu$	Day	0.10 K
	Night	-0.08 K
	Both	0 K
$\sigma$	Day	0.54 K
	Night	0.43 K
	Both	0.49 K
median	Day	0.05 K
	Night	-0.13 K
	Both	-0.07 K
rsd	Day	0.28 K
	Night	0.20 K
	Both	0.25 K

### Distribution of deviation of SST. NOAA-18





# Comparison

No SST analysis  
used in any of  
these algorithms

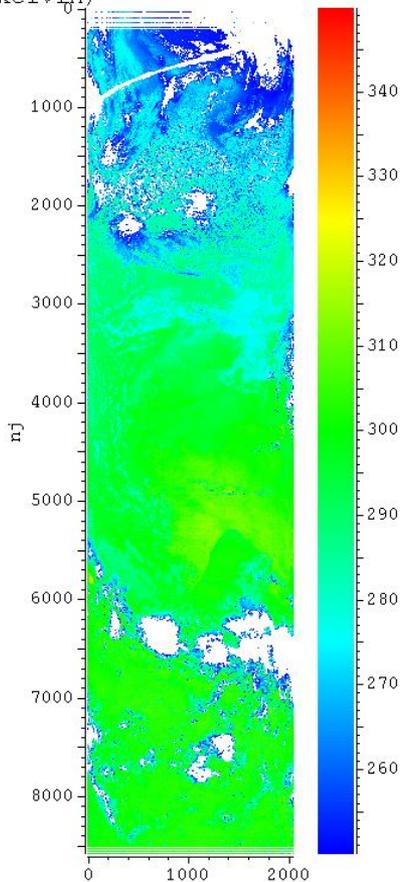
		2 channel linear	BOM 2011	2/3 channel linear	2/3 channel NLSST	Tri-linear
Model complexity		3 terms Includes $\theta_z$	9 terms	Day / Night 2 equations	Day / Night 2 equations	"3" terms
$\mu$	Day	0.09 K	0.08 K	0 K	0 K	0.10 K
	Night	-0.07 K	-0.06 K	0 K	0 K	-0.08 K
	Both	0 K	0 K	0 K	0 K	0 K
$\sigma$	Day	0.56 K	0.48 K	0.56 K	0.56 K	0.54 K
	Night	0.58 K	0.49 K	0.44 K	0.42 K	0.43 K
	Both	0.58 K	0.49 K	0.50 K	0.48 K	0.49 K
median	Day	0.05 K	0.03 K	-0.05 K	-0.05 K	0.06 K
	Night	-0.11 K	-0.09 K	-0.05 K	-0.05 K	-0.14 K
	Both	-0.04 K	-0.03 K	-0.05 K	-0.05 K	-0.07 K
rsd	Day	0.30 K	0.22 K	0.30 K	0.29 K	0.28 K
	Night	0.30 K	0.23 K	0.21 K	0.20 K	0.20 K
	Both	0.31 K	0.23 K	0.24 K	0.23 K	0.25 K



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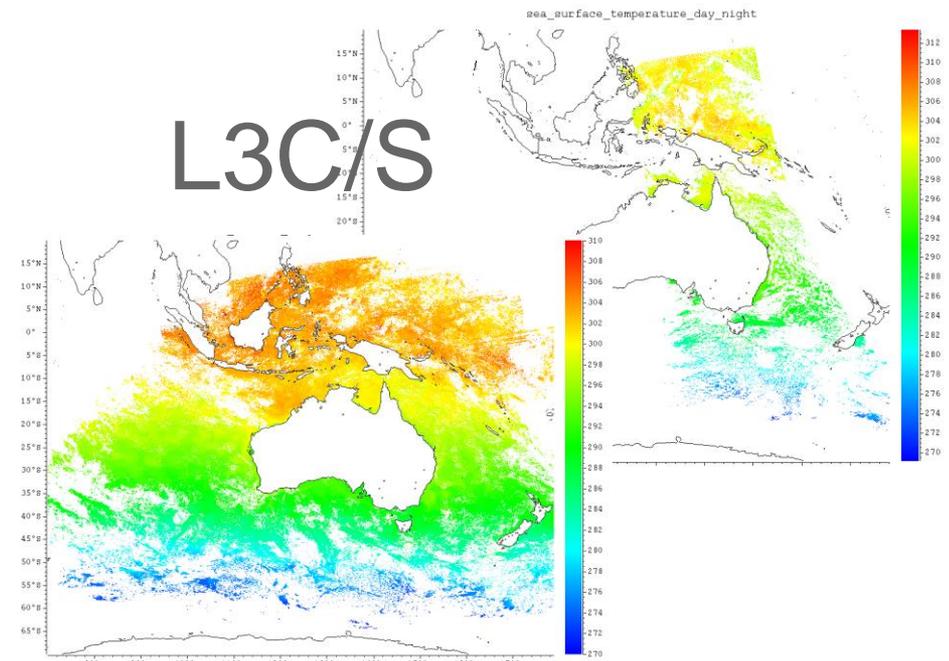
# Availability (from July 2013)

experimental sea surface skin  
temperature  
sea\_surface\_temperature\_day\_night  
(kelvin)



L2P

- ABOM GHRSSST SST products
- Experimental field **L3U**



sea\_surface\_temperature\_day\_night

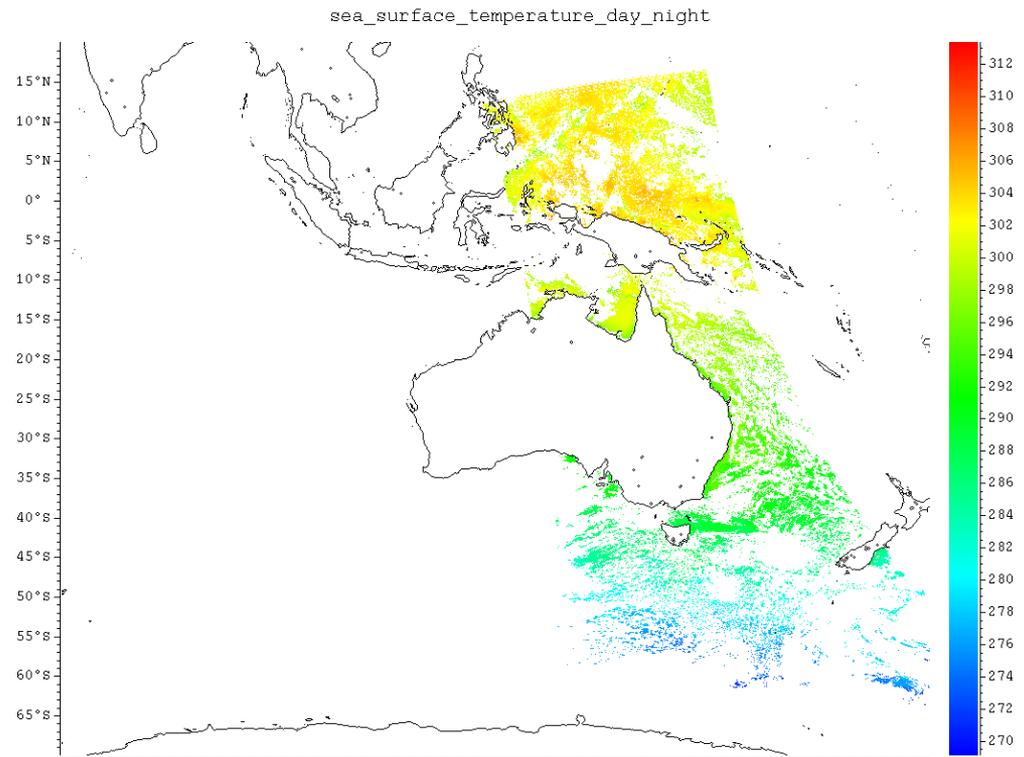


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# Further work

- Compensation of  $\Theta_z$  decoupled from buoy measurements – we have shown that this is possible, but definitely some room for improvement.
- Allows anomalous  $T_3$  to be detected independent of *in situ* measurements.
- It may be possible to generalize to 2<sup>nd</sup> Dominant factor characterization - independent of *in situ* measurements, perhaps using spatial correlations.
- Tuning to *in situ* involves a small number of parameters and is thus less sensitive to noise, and instabilities in fitting. Same parameters used for day and night
- Greater stability allows the tuning to be effectively performed on a rolling time window.





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Thank you...

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